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24. CHAPTER 2. E2.4. Mathematical Models of Systems. Since $R(s) = 1/s$, we have $Y(s) = 6(s + 50) / [s(s + 30)(s + 10)]$. The partial fraction expansion of $Y(s)$ is given by $A_1/s + A_2/(s + 30) + A_3/(s + 10)$.

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Most modern PID controls in industry are implemented as computer software in distributed control systems (DCS), programmable logic controllers (PLCs), or discrete compact controllers.. Electronic analog controllers. Electronic analog PID control loops were often found within more complex electronic systems, for example, the head positioning of a disk drive, the power conditioning of a power ...

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With modern computer control systems, scaling for unit conversions is becoming more common in the controller signal path. Sometimes a display has been scaled but the signal in the loop path has not. You must pay attention to this detail and make sure you are using the correct units in your computations. There is more discussion in this article.

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